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one of the parts has a reference shaft connected in non-rotary manner thereto and which projects at least to the other part, said movement of said first part is additionally removable by means of said shaft on a second side facing said second part and remote from said first end side.

Please add the following new claims.

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25. (New) A gear arrangement comprising:

a first part having a first side and a second side diametrically opposite each other;  
a drive shaft rotatably connected to said first part at said first side of said first part;  
a second part rotatably connected to said first part at said second side of said first part,  
said second part being operatively connected to said drive shaft, said second side having a power take off side arranged diametrically opposite said first part.;  
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a reference shaft fixed to said first part and extending through said second part to said power take off side of said second part.

26. (New) An arrangement in accordance with claim 25, wherein:

said power take off side of said second part is accessible and connectable to an additional part to move the additional part due to rotation of said second part.

27. (New) An arrangement in accordance with claim 25, further comprising:

a first robot arm connected to said first part;  
a second robot arm connected to said second part.